Sketch In, Sketch Out: Accelerating both Learning and Inference for Structured Prediction with Kernels



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Emblematic example of metabolite identification (Brouard et al., 2016a; Schymanski et al., 2017):



Structured prediction in supervised settings

Supervised settings: *n* i.i.d. training sample $(x_i, y_i)_{i=1}^n \in (\mathcal{X}, \mathcal{Y})^n \sim \rho$



Given a loss function $\Delta:\mathcal{Y}^2\to\mathbb{R}$

$$f^* = \underset{f:\mathcal{X}\to\mathcal{Y}}{\operatorname{arg\,inf}} \ \mathbb{E}_{(x,y)\sim\rho}[\Delta(f(x),y)] \approx \underset{f:\mathcal{X}\to\mathcal{Y}}{\operatorname{arg\,inf}} \ \frac{1}{n} \sum_{i=1}^n \Delta(f(x_i),y_i) = \hat{f}$$

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How to design a loss Δ taking into account the structure of \mathcal{Y} ?

- 1. Input Output Kernel Regression
- 2. Sketched Input Sketched Output Kernel Regression
- 3. Theoretical guarantees
- 4. Experiments
- 5. Conclusion

Input Output Kernel Regression

Linear method after embedding through feature map $\psi_{\mathcal{Y}} : \mathcal{Y} \to \mathcal{H}_{\mathcal{Y}}$: choice of kernel \iff choice of representation



 $\langle \boldsymbol{\psi}_{\boldsymbol{\mathcal{Y}}}(y), \boldsymbol{\psi}_{\boldsymbol{\mathcal{Y}}}(y') \rangle_{\boldsymbol{\mathcal{H}}_{\boldsymbol{\mathcal{Y}}}} = \boldsymbol{k}_{\boldsymbol{\mathcal{Y}}}(y, y')$: relevant similarity measure over $\boldsymbol{\mathcal{Y}}$

$$\implies \mathbf{\Delta}(\mathbf{y},\mathbf{y}') = \|\boldsymbol{\psi}_{\boldsymbol{\mathcal{Y}}}(\mathbf{y}) - \boldsymbol{\psi}_{\boldsymbol{\mathcal{Y}}}(\mathbf{y}')\|_{\boldsymbol{\mathcal{H}}_{\boldsymbol{\mathcal{Y}}}}^2 = 2 - 2\mathbf{k}_{\boldsymbol{\mathcal{Y}}}(\mathbf{y},\mathbf{y}')$$

 $(\forall y \in \mathcal{Y}, \| \boldsymbol{\psi}_{\boldsymbol{\mathcal{Y}}} \|_{\boldsymbol{\mathcal{H}}_{\boldsymbol{\mathcal{Y}}}} = 1$ without loss of generality)

Versatility: tackle various tasks through an appropriate choice of $\psi_{\mathcal{Y}}$ (e.g. SOTA performance on metabolite identification (Brouard et al., 2016a) and label ranking (Korba et al., 2018) datasets)

Output Kernel Regression: a surrogate approach

Surrogate (2-step) method (Weston et al., 2003; Cortes et al., 2005; Brouard et al., 2011; Kadri et al., 2013):

1.
$$\hat{h} = \underset{h:\mathcal{X}\to\mathcal{H}_{\mathcal{Y}}}{\arg\min} \frac{1}{n} \sum_{i=1}^{n} \|h(x_i) - \psi_{\mathcal{Y}}(y_i)\|_{\mathcal{H}_{\mathcal{Y}}}^2$$
 (training step)
2. $\hat{f}(x) = d \circ \hat{h}(x) = \underset{y \in \mathcal{Y}}{\arg\min} \|\hat{h}(x) - \psi_{\mathcal{Y}}(y)\|_{\mathcal{H}_{\mathcal{Y}}}^2$ (inference step)



Theoretical guarantees: for measurable $h : \mathcal{X} \to \mathcal{H}_{\mathcal{Y}}$ and $f = d \circ h$, *f*'s excess risk is bounded by *h*'s excess risk (Ciliberto et al., 2020)

Input Output Kernel Regression



IOKR: Weston et al. (2003); Cortes et al. (2005); Brouard et al. (2011); Kadri et al. (2013); Brouard et al. (2016b); Korba et al. (2018)

IOKR: training and inference complexities

1. Training: $\hat{h}(x) = \sum_{i=1}^{n} \hat{\alpha}(x)_i \psi_{\mathcal{Y}}(y_i)$ where $\hat{\alpha}(x) = (\underbrace{K_X + n\lambda I_n}_{n \times n})^{-1} k_X^x = \widehat{\Omega} k_X^x$

 $\implies \mathcal{O}(\mathbf{n}^3)$ time complexity

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2. Inference:
$$\hat{f}(x) = \underset{y \in \mathcal{Y}}{\arg \max} \sum_{i=1}^{n} \hat{\alpha}(x)_i k_{\mathcal{Y}}(y_i, y) = k_{\chi}^{\chi^T} \widehat{\Omega} k_{\gamma}^{y}$$

- Test set: $X^{te} = \{x_1^{te}, \dots, x_{n_{te}}^{te}\}$ of size n_{te}
- Candidate set: $Y^{c} = \{y_{1}^{c}, \dots, y_{n_{c}}^{c}\}$ of size n_{c}



$$\hat{f}(x_i^{\text{te}}) = y_j^{\text{c}}$$
 where $j = \underset{1 \leq j \leq n_c}{\arg \max} [K_{\chi}^{\text{te},\text{tr}} \widehat{\Omega} K_{\gamma}^{\text{tr},\text{c}}]_{ij}$

 $\implies \mathcal{O}(n_{te}nn_{c})$ time complexity if $n_{te} < n \leq n_{c}$

1. Scalability: obtain $\tilde{f} = d \circ \tilde{h}$, computationally efficient version of $\hat{f} = d \circ \hat{h}$, when learning from big data, i.e. large *n*

2. Theory: obtain excess risk bound of $\tilde{f} = d \circ \tilde{h}$

Key tool for scalability: Random Fourier Features vs Sketching

a) Random Fourier Features (Rahimi and Recht, 2007; Sriperumbudur and Szabó, 2015): for $m_{\mathcal{Y}} \ll n$,

 $\langle \psi_{\mathcal{Y}}(\mathbf{y}), \psi_{\mathcal{Y}}(\mathbf{y}') \rangle_{\mathcal{H}_{\mathcal{Y}}} \approx \langle \tilde{\psi}_{\mathcal{Y}}(\mathbf{y}), \tilde{\psi}_{\mathcal{Y}}(\mathbf{y}') \rangle_{\mathbb{R}^{m} \mathcal{Y}}$

 $\implies \mathbf{\Delta}(y, y') = \| \boldsymbol{\psi}_{\mathbf{\mathcal{Y}}}(y) - \boldsymbol{\psi}_{\mathbf{\mathcal{Y}}}(y') \|_{\mathcal{H}_{\mathbf{\mathcal{Y}}}}^2 \approx \| \tilde{\boldsymbol{\psi}}_{\mathbf{\mathcal{Y}}}(y) - \tilde{\boldsymbol{\psi}}_{\mathbf{\mathcal{Y}}}(y') \|_{\mathbb{R}^m \mathcal{Y}}^2 = \widetilde{\mathbf{\Delta}}(y, y')$ $\implies \widetilde{\mathbf{\Delta}} \text{ approximated loss}$

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b) Sketching (Williams and Seeger, 2001; Rudi et al., 2015; Yang et al., 2017): for $m_{\mathcal{Y}} \ll n$, $R_{\mathcal{Y}} \in \mathbb{R}^{m_{\mathcal{Y}} \times n}$

span
$$\left(\left(\psi_{\mathcal{Y}}(y_i)\right)_{i=1}^{n}\right) \leftarrow \text{span}\left(\left(\sum_{j=1}^{n} [R_{\mathcal{Y}}]_{ij}\psi_{\mathcal{Y}}(y_j)\right)_{i=1}^{m_{\mathcal{Y}}}\right)$$

 \Rightarrow Δ remains unchanged!

Sketched Input Sketched Output Kernel Regression

Motivation: build a **low-rank** approximation \tilde{h} of \hat{h} thanks to **input and output** random projectors \tilde{P}_X and \tilde{P}_Y to obtain a **scalable** predictor \tilde{f} together with an **excess risk bound**

For an i.i.d. sample $(z_i)_{i=1}^n \in \mathbb{Z}^n \sim \rho_z$:

- $S_Z : f \in \mathcal{H}_Z \mapsto (1/\sqrt{n})(\langle f, \psi_Z(z_1) \rangle_{\mathcal{H}_Z}, \dots, \langle f, \psi_Z(z_n) \rangle_{\mathcal{H}_Z})^\top \in \mathbb{R}^n$ sampling operator
- $S_Z^{\#} : \alpha \in \mathbb{R}^n \mapsto (1/\sqrt{n}) \sum_{i=1}^n \alpha_i \psi_Z(z_i) \in \operatorname{span} \left((\psi_Z(z_i))_{i=1}^n \right)$ its adjoint
- $\cdot \ \mathcal{C}_{\mathcal{Z}} = \mathbb{E}_{z}[\psi_{\mathcal{Z}}(z) \otimes \psi_{\mathcal{Z}}(z)]$ covariance operator
- $\widehat{C}_{Z} = (1/n) \sum_{i=1}^{n} \psi_{Z}(z_{i}) \otimes \psi_{Z}(z_{i}) = S_{Z}^{\#} S_{Z}$ its empirical counterpart: $\widehat{C}_{Z} : \mathcal{H}_{Z} \to \operatorname{span}\left((\psi_{Z}(z_{i}))_{i=1}^{n}\right)$

Low-rank estimator: from IOKR to SISOKR



Low-rank estimator: from IOKR to SISOKR



$$\widetilde{P}_{Z}: \mathcal{H}_{Z} o \widetilde{\mathcal{H}}_{Z}$$
 where $\widetilde{\mathcal{H}}_{Z} \coloneqq \operatorname{span} \left(\left(\sum_{j=1}^{n} [R_{Z}]_{ij} \psi_{Z}(z_{j}) \right)_{i=1}^{m_{Z}} \right)$

How to build these projectors?

Construction of the orthogonal projector \widetilde{P}_Z

- $\widehat{C}_Z = S_Z^{\#} S_Z = (1/n) \sum_{i=1}^n \psi_{\mathcal{Z}}(z_i) \otimes \psi_{\mathcal{Z}}(z_i)$
- $\widetilde{C}_{Z} = S_{Z}^{\#} R_{Z}^{\top} R_{Z} S_{Z} = \frac{1}{n} \sum_{l=1}^{m_{Z}} \left(\sum_{i=1}^{n} R_{Z_{ij}} \psi_{Z}(z_{i}) \right) \otimes \left(\sum_{j=1}^{n} R_{Z_{ij}} \psi_{Z}(z_{j}) \right)$
- $\widetilde{K}_Z = R_{\mathcal{Z}} K_Z R_{\mathcal{Z}}^{\top}$, and $\left\{ \left(\sigma_i(\widetilde{K}_Z), \widetilde{\mathbf{u}}_i^Z \right), i \in [m_{\mathcal{Z}}] \right\}$ its eigenpairs
- $p_Z = \operatorname{rank}\left(\widetilde{K}_Z\right)$, and for all $1 \le i \le p_Z$, $\tilde{\boldsymbol{e}}_i^Z = \sqrt{\frac{n}{\sigma_i(\widetilde{K}_Z)}} \mathbf{S}_Z^{\#} \mathbf{R}_Z^{\top} \tilde{\mathbf{u}}_i^Z \in \mathcal{H}_Z$

Construction of the orthogonal projector \widetilde{P}_Z

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- $\widetilde{C}_{Z} = S_{Z}^{\#} R_{Z}^{\top} R_{Z} S_{Z} = \frac{1}{n} \sum_{l=1}^{m_{Z}} \left(\sum_{i=1}^{n} R_{Z_{ij}} \psi_{Z}(z_{i}) \right) \otimes \left(\sum_{j=1}^{n} R_{Z_{ij}} \psi_{Z}(z_{j}) \right)$
- $\widetilde{K}_Z = R_Z K_Z R_Z^{\top}$, and $\left\{ \left(\sigma_i(\widetilde{K}_Z), \widetilde{\mathbf{u}_i^Z} \right), i \in [m_Z] \right\}$ its eigenpairs

•
$$p_Z = \operatorname{rank}\left(\widetilde{K}_Z\right)$$
, and for all $1 \le i \le p_Z$, $\tilde{e}_i^Z = \sqrt{\frac{n}{\sigma_i(\widetilde{K}_Z)}} S_Z^{\#} R_Z^{\top} \tilde{u}_i^Z \in \mathcal{H}_Z$

Proposition (El Ahmad et al., 2024)

The \tilde{e}_i^Z s are the eigenfunctions, associated to the eigenvalues $\sigma_i(\tilde{K}_Z)/n$, of \tilde{C}_Z , whose range is $\operatorname{span}((\sum_{j=1}^n R_{\mathcal{Z}_{ij}}\psi_{\mathcal{Z}}(z_j))_{i=1}^{m_{\mathcal{Z}}})$. Then, $\tilde{E}^Z = (\tilde{e}_1^Z, \dots, \tilde{e}_{p_Z}^Z)$ is an orthonormal basis of $\operatorname{span}((\sum_{j=1}^n R_{\mathcal{Z}_{ij}}\psi_{\mathcal{Z}}(z_j))_{i=1}^{m_{\mathcal{Z}}})$, and \tilde{P}_Z writes as $\tilde{P}_Z = \sum_{j=1}^{p_Z} \langle \cdot, \tilde{e}_i^Z \rangle_{\mathcal{H}_{\mathcal{Z}}} \tilde{e}_i^Z = (R_{\mathcal{Z}}S_Z)^\# (R_{\mathcal{Z}}S_Z(R_{\mathcal{Z}}S_Z)^\#)^\dagger R_{\mathcal{Z}}S_Z$.

Related works on Nyström: Yang et al. (2012); Rudi et al. (2015)

Sketched Input Sketched Output Kernel Regression estimator



Sketched Input Sketched Output Kernel Regression estimator



Inversion complexity: $\mathcal{O}(n^3) \rightarrow \mathcal{O}(\max(m_{\mathcal{X}}^3, m_{\mathcal{Y}}^3))$

Complexity of $R_{\mathcal{Z}}K_{\mathcal{Z}}$: depends on the sketching matrix, between $\mathcal{O}(nm_{\mathcal{Z}})$ and $\mathcal{O}(n^2m_{\mathcal{Z}})$

 \implies Training complexity reduced thanks to input sketching!

$$\widetilde{f}(x) = \arg\max_{y \in \mathcal{Y}} \sum_{i=1}^{n} \widetilde{\alpha}(x)_{i} \mathbf{k}_{\mathcal{Y}}(y_{i}, y) = \arg\max_{y \in \mathcal{Y}} k_{X}^{x^{T}} R_{\mathcal{X}}^{\top} \widetilde{\Omega} R_{\mathcal{Y}} \mathbf{k}_{Y}^{y}$$
$$\underbrace{K_{X}^{\text{te},\text{tr}} R_{\mathcal{X}}^{\top}}_{n_{\text{te}} \times m_{\mathcal{X}}} \underbrace{\widetilde{\Omega}}_{m_{\mathcal{X}} \times m_{\mathcal{Y}}} \underbrace{R_{Y}^{\top} R_{\mathcal{X}}^{\top} \widetilde{\Omega} R_{\mathcal{Y}} \mathbf{k}_{Y}^{y}}_{m_{\mathcal{Y}} \times n_{c}}$$
$$\widetilde{f}(x_{i}^{\text{te}}) = y_{j}^{c} \quad \text{where} \quad j = \arg\max_{1 \le j \le n_{c}} [K_{X}^{\text{te},\text{tr}} R_{\mathcal{X}}^{\top} \widetilde{\Omega} R_{\mathcal{Y}} K_{Y}^{\text{tr},c}]_{ij}$$

$$\widetilde{f}(x) = \arg\max_{y \in \mathcal{Y}} \sum_{i=1}^{n} \widetilde{\alpha}(x)_{i} \mathbf{k}_{\mathcal{Y}}(y_{i}, y) = \arg\max_{y \in \mathcal{Y}} k_{\mathcal{X}}^{xT} \mathbf{R}_{\mathcal{X}}^{\top} \widetilde{\Omega} \mathbf{R}_{\mathcal{Y}} \mathbf{k}_{Y}^{y}$$
$$\underbrace{\mathcal{K}_{\mathcal{X}}^{\mathsf{te}, \mathsf{tr}} \mathbf{R}_{\mathcal{X}}^{\top}}_{n_{\mathsf{te}} \times m_{\mathcal{X}}} \underbrace{\widetilde{\Omega}}_{m_{\mathcal{X}} \times m_{\mathcal{Y}}} \underbrace{\mathcal{R}_{\mathcal{Y}} \mathcal{K}_{Y}^{\mathsf{tr}, \mathsf{c}}}_{m_{\mathcal{Y}} \times n_{\mathsf{c}}}$$
$$\widetilde{f}(x_{i}^{\mathsf{te}}) = y_{j}^{\mathsf{c}} \quad \text{where} \quad j = \arg\max_{1 \le j \le n_{\mathsf{c}}} [\mathcal{K}_{\mathcal{X}}^{\mathsf{te}, \mathsf{tr}} \mathbf{R}_{\mathcal{X}}^{\top} \widetilde{\Omega} \mathbf{R}_{\mathcal{Y}} \mathcal{K}_{Y}^{\mathsf{tr}, \mathsf{c}}]_{ij}$$

Decoding complexity: $\mathcal{O}(n_{te}nn_{c}) \rightarrow \mathcal{O}(n_{te}m_{\mathcal{Y}}n_{c})$ if $n_{te} \leq m_{\mathcal{X}}, m_{\mathcal{Y}} < \mathbf{n} \leq \mathbf{n_{c}}$

 \implies Inference complexity reduced thanks to output sketching!

Scalability √!

Theoretical guarantees

Let

$$\mathcal{R}(f) = \mathbb{E}_{(x,y) \sim \rho}[\Delta(f(x), y)],$$

and

$$f^* = \underset{f:\mathcal{X}\to\mathcal{Y}}{\operatorname{arg\,inf}} \mathbb{E}_{(x,y)\sim\rho}[\boldsymbol{\Delta}(f(x),y)],$$

we want to control

$$\mathcal{R}(ilde{f}) - \mathcal{R}(f^*) \leq ~?$$

Assumptions

Asm. 1 (Attainability): Recall that $h^*(x) := \mathbb{E}_Y[\psi_{\mathcal{Y}}(Y) \mid X = x]$. There exists $H : \mathcal{H}_{\mathcal{X}} \to \mathcal{H}_{\mathcal{Y}}$ with $\|H\|_{HS} < +\infty$ such that

 $h^*(x) = H\psi_{\mathcal{X}}(x) \quad \forall x \in \mathcal{X}.$

Asm. 2 (Bounded kernel): there exists $\kappa_{\mathcal{Z}} > 0$ such that

 $k_{\mathcal{Z}}(z,z) \leq \kappa_{\mathcal{Z}}^2 \quad \forall z \in \mathcal{Z}.$

Asm. 3 (Capacity condition): there exists $\gamma_{\mathcal{Z}} \in [0, 1]$ such that

 $Q_{\mathcal{Z}} := \mathsf{Tr}(\mathcal{C}_{\mathcal{Z}}^{\gamma_{\mathcal{Z}}}) < +\infty.$

Asm. 4 (Embedding property): there exists $b_{\mathcal{Z}} > 0$ and $\mu_{\mathcal{Z}} \in [0, 1]$ such that almost surely

 $\psi_{\mathcal{Z}}(Z) \otimes \psi_{\mathcal{Z}}(Z) \preceq b_{\mathcal{Z}} C_{\mathcal{Z}}^{1-\mu_{\mathcal{Z}}}.$

Asm. 5 (Sub-Gaussian sketches): $R_{\mathcal{Z}} \in \mathbb{R}^{m_{\mathcal{Z}} \times n}$ composed with i.i.d. entries s.t. (i) $\mathbb{E} \left[R_{\mathcal{Z}_{ij}} \right] = 0$, (ii) $\mathbb{E} \left[R_{\mathcal{Z}_{ij}}^2 \right] = 1/m_{\mathcal{Z}}$ and (iii) $R_{\mathcal{Z}_{ij}} \sim \frac{\nu_{\mathcal{Z}}^2}{m_{\mathcal{Z}}^2} - \text{sub-Gaussian with } \nu_{\mathcal{Z}} \geq 1$.

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Theorem: SISOKR learning rates (El Ahmad et al., 2024)

Under Asm. 1, 2, 3, 4 and 5, if for all $y \in \mathcal{Y}, \|\psi_{\mathcal{Y}}(y)\|_{\mathcal{H}_{\mathcal{Y}}} = \kappa_{\mathcal{Y}}$, for $\mathcal{Z} \in \{\mathcal{X}, \mathcal{Y}\}$ and for $n \in \mathbb{N}$ sufficiently large such that $\frac{9}{n} \log(n/\delta) \le n^{-\frac{1}{1+\gamma_{\mathcal{Z}}}} \le \|C_{\mathcal{Z}}\|_{op}/2$, and for sketching sizes $m_{\mathcal{Z}}, \in \mathbb{N}$ such that

$$m_{\mathcal{Z}} \gtrsim \max\left(\nu_{\mathcal{Z}}^2 n^{\frac{\gamma_{\mathcal{Z}} + \mu_{\mathcal{Z}}}{1 + \gamma_{\mathcal{Z}}}}, \nu_{\mathcal{Z}}^4 \log\left(1/\delta\right)\right),$$

then with probability 1 – δ

$$\mathbb{E}[\|\tilde{h}(x) - h^*(x)\|_{\mathcal{H}_{\mathcal{Y}}}^2]^{\frac{1}{2}} \lesssim \log\left(4/\delta\right) n^{-\frac{1-\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}}}{2(1+\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}})}},$$

and

$$\mathcal{R}(\tilde{f}) - \mathcal{R}(f^*) \lesssim \mathbb{E}[\|\tilde{h}(x) - h^*(x)\|_{\mathcal{H}_{\mathcal{Y}}}^2]^{\frac{1}{2}} \lesssim \log\left(4/\delta\right) n^{-\frac{1-\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}}}{2(1+\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}})}}$$

Experiments

1) $n = 10\ 000, \ \mathcal{X} = \mathcal{Y} = \mathbb{R}^d, \ d = 300, \ k_{\mathcal{X}} \text{ and } k_{\mathcal{Y}} \text{ linear kernels} \implies \mathcal{H}_{\mathcal{X}} = \mathcal{H}_{\mathcal{Y}} = \mathbb{R}^d$

2) Construct covariance matrices C_X and E such that $\sigma_k(C_X) = k^{-3/2}$ and $\sigma_k(E) = 0.2k^{-1/10}$

3) Draw $H_0 \sim \mathcal{N}(0, I_d)$, and for $i \leq n, x_i \sim \mathcal{N}(0, C_{\mathcal{X}}), \epsilon_i \sim \mathcal{N}(0, E)$,

 $y_i = C_{\mathcal{X}} H_0 x_i + \epsilon_i$

4) 20/n-SR input and output sketches (sub-Gaussian)

Synthetic least squares regression



Synthetic least squares regression



Multi-Label Classification: Statistical Performance

Method	Method Bibtex Bookm	
SISOKR	44.1 ± 0.07	$\textbf{39.3} \pm \textbf{0.61}$
ISOKR	44.8 ± 0.01	NA
SIOKR	44.7 ± 0.09	39.1 ± 0.04
IOKR	44.9	NA
LR	37.2	30.7
NN	38.9	33.8
SPEN	42.2	34.4
PRLR	44.2	34.9
DVN	44.7	37.1

 Table 1: F1 score on tag prediction from text data.

Table 2: Comparison of training/inference computation times (in seconds).

Method	Bibtex	Bookmarks
SISOKR	1.41 ± 0.03 / 0.46 ± 0.01	118 ± 1.5 / 20 ± 0.2
ISOKR	2.51 ± 0.06 / 0.58 ± 0.01	NA
SIOKR	1.99 ± 0.07 / 1.22 ± 0.03	354 \pm 2.1 / 297 \pm 2.1
IOKR	2.54 / 1.18	NA

Synthetic and real-world experiments: take-home messages

1) a) Input sketching: mainly accelerates the training phase

1) b) Output sketching: accelerates the inference phase

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Synthetic and real-world experiments: take-home messages

- 1) a) Input sketching: mainly accelerates the training phase
- 1) b) Output sketching: accelerates the inference phase
- 2) Optimal computational/statistical trade-off: statistical performance converges when m_{χ}/m_{y} increases \implies no need to set them too high!
- 3) Benefits from sketching w.r.t. the number of training data n:

small	intermediate	large
No benefit	SISOKR accelerates IOKR	SISOKR is tractable n
from sketching	while being as accurate	unlike IOKR

Conclusion

- SISOKR: sketching on both input/output kernels to accelerate both training/inference steps
- Sketching as a way to build orthogonal projectors onto low-dimensional subspace of the feature space
- Excess risk bound leading to a consistent theoretical analysis of SISOKR
- Experiments: SISOKR accelerates IOKR or make it tractable

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Table 3: Time and space complexities at training and inference for the IOKR and SISOKR algorithms with sub-sampling, *p*-sparsified ($p \in (0, 1]$) or Gaussian sketching, for a test set of size n_{te} and a candidate set of size n_c , such that $n_{te} \leq m_{\mathcal{X}}, m_{\mathcal{Y}} < n \leq n_c$. For the sake of simplicity, we omit the $\mathcal{O}(\cdot)$ in the following.

	Trair	Inference		
Method	Time Space		Time	Space
IOKR SISOKR (sub-sampling) SISOKR (p-sparsified) SISOKR (Gaussian)	n^{3} $\max(m_{\mathcal{X}}, m_{\mathcal{Y}})n$ $\max(m_{\mathcal{X}}, m_{\mathcal{Y}})^{2}pn$ $\max(m_{\mathcal{X}}, m_{\mathcal{Y}})n^{2}$	n^2 max $(m_X, m_Y)n$ max $(m_X, m_Y)pn$ n^2	n _{te} nn _c n _{te} myn _c max(n _{te} , nmyp)myn _c nmyn _c	nn _c myn _c npmyn _c nn _c

Goal: set the minimal value of $m_{\mathbb{Z}}$ s.t. it captures the information contained in the empirical covariance operator $\widehat{C}_{Z} = \frac{1}{n} \sum_{i=1}^{n} \psi_{\mathbb{Z}}(z_{i}) \otimes \psi_{\mathbb{Z}}(z_{i})$

However: computing the SVD of \widehat{C}_Z is costing, i.e. $\mathcal{O}(n^3)$ in time.

1. Approximate leverage scores of \hat{C}_X and \hat{C}_Y

2. Empirical approach: given training/inference budgets of time $T_{\rm tr}/T_{\rm inf}$, set low $m_{\mathcal{X}}$ and $m_{\mathcal{Y}}$ and evaluate the performance of \tilde{f} until reaching one of the following condition:

- \cdot convergence of the performance of \tilde{f}
- training time attains $T_{\rm tr}$ or inference time attains $T_{\rm te}$

Selection of $m_{\mathcal{X}}$

$$\tilde{h}^{\text{SIOKR}}(x) = \sum_{i=1}^{n} \tilde{\alpha}_{i}^{\text{SIOKR}}(x) \psi_{\mathcal{Y}}(y_{i}) \text{ where}$$
$$\tilde{\alpha}^{\text{SIOKR}}(x) = K_{\chi} R_{\mathcal{X}}^{\top} (R_{\mathcal{X}} K_{\chi}^{2} R_{\mathcal{X}}^{\top} + n\lambda R_{\mathcal{X}} K_{\chi} R_{\mathcal{X}}^{\top})^{\dagger}$$

Set the optimal $m_{\mathcal{X}}$ according to a training budget of time $T_{\rm tr}$ and the performance of $\tilde{h}^{\rm SIOKR}$ in terms of surrogate regression error on the validation set, i.e. minimizing

$$\begin{split} &\sum_{i=1}^{n_{val}} \left\| \tilde{h}^{\mathsf{SIOKR}}(\boldsymbol{x}_{i}^{val}) - \psi_{\mathcal{Y}}(\boldsymbol{y}_{i}^{val}) \right\|_{\mathcal{H}_{\mathcal{Y}}}^{2} \\ &= \sum_{i=1}^{n_{val}} \tilde{\alpha}^{\mathsf{SIOKR}} \left(\boldsymbol{x}_{i}^{val} \right)^{\top} \mathcal{K}_{\mathsf{Y}} \tilde{\alpha}^{\mathsf{SIOKR}} \left(\boldsymbol{x}_{i}^{val} \right) - 2 \tilde{\alpha}^{\mathsf{SIOKR}} \left(\boldsymbol{x}_{i}^{val} \right)^{\top} \mathcal{K}_{\mathsf{Y}}^{val} + \mathcal{K}_{\mathcal{Y}}(\boldsymbol{y}_{i}^{val}, \boldsymbol{y}_{i}^{val}) \end{split}$$

 \implies allows to cope with the inference phase

Set the optimal $m_{\mathcal{Y}}$ according to an inference budget of time T_{inf} and the performance of the *perfect h* estimator on the validation set, i.e.

$$h:(x,y)\mapsto \widetilde{P}_Y\psi_{\mathcal{Y}}(y)$$

$$f(x_i^{\mathsf{val}}) = y_j^{\mathsf{c}} \quad \text{where} \quad j = \underset{1 \le j \le n_{\mathsf{c}}}{\arg \max} \left[K_{Y}^{\mathsf{val},\mathsf{tr}} R_{\mathcal{Y}}^{\top} \widetilde{K}_{Y}^{\dagger} R_{\mathcal{Y}} K_{Y}^{\mathsf{tr},\mathsf{c}} \right]_{ij}$$

 \implies allows to cope with the training phase

Theory: previous works and differences

Rudi et al. (2015):

- 1. scalar kernel Ridge regression
- 2. sketching **only** applied in the **input** feature space
- 3. Nyström approximation with uniform or approximate leverage scores sampling

Ciliberto et al. (2020):

- 1. **vector-valued** kernel Ridge regression, with possibly infinite-dimensional outputs
- 2. no approximation considered

This work (El Ahmad et al., 2024):

- 1. **vector-valued** kernel Ridge regression, with possibly infinite-dimensional outputs
- 2. sketching applied in **both** the **input and output** feature space
- 3. generic sub-Gaussian sketches

Related recent works on Koopman operators: (Meanti et al., 2023; Caldarelli et al., 2024)

SISOKR excess risk bound

Theorem (El Ahmad et al., 2024)

Let $\delta \in [0, 1]$, $n \in \mathbb{N}$ sufficiently large such that $\lambda = n^{-1/(1+\gamma_{\mathcal{X}})} \ge \frac{9\kappa_{\mathcal{X}}^2}{n} \log(\frac{n}{\delta})$. Under Asm. 1, 2, 3 and 4, the following holds with probability at least $1 - \delta$

$$\mathbb{E}[\|\tilde{h}(x) - h^*(x)\|_{\mathcal{H}_{\mathcal{Y}}}^2]^{\frac{1}{2}} \leq \frac{\mathsf{S}(n)}{\mathsf{C}_2} + \mathsf{C}_2 A_{\rho_x}^{\psi_{\mathcal{X}}}(\widetilde{P}_{\mathcal{X}}) + A_{\rho_y}^{\psi_{\mathcal{Y}}}(\widetilde{P}_{\mathcal{Y}})$$

where

$$\begin{split} S(n) &= c_1 \log(4/\delta) n^{-\frac{1}{2(1+\gamma_{\mathcal{X}})}} & \text{(regression error)} \\ A_{\rho_z}^{\psi_{\mathcal{Z}}}(\widetilde{P}_Z) &= \mathbb{E}_{Z}[\|(\widetilde{P}_Z - I_{\mathcal{H}_{\mathcal{Z}}})\psi_{\mathcal{Z}}(Z)\|_{\mathcal{H}_{\mathcal{Z}}}^2]^{\frac{1}{2}} & \text{(sketching reconstruction error)} \end{split}$$

and $c_1, c_2 > 0$ are constants independent of n and δ defined in the proofs.

Theorem (El Ahmad et al., 2024)

Under Asm. 1, 2, 3 and 4, for $\delta \in (0, 1/e]$, $n \in \mathbb{N}$ sufficiently large such that $\frac{9}{n} \log(n/\delta) \le n^{-\frac{1}{1+\gamma_{\mathcal{Z}}}} \le \|C_{\mathcal{Z}}\|_{op}/2$, then if

$$m_{\mathcal{Z}} \geq c_4 \max\left(\nu_{\mathcal{Z}}^2 n^{\frac{\gamma_{\mathcal{Z}}+\mu_{\mathcal{Z}}}{1+\gamma_{\mathcal{Z}}}}, \nu_{\mathcal{Z}}^4 \log\left(1/\delta\right)\right),$$

then with probability 1 – δ

$$\mathbb{E}_{z}[\|(\widetilde{P}_{Z}-I_{\mathcal{H}_{Z}})\psi_{\mathcal{Z}}(z)\|_{\mathcal{H}_{Z}}^{2}] \leq c_{3}n^{-\frac{1-\gamma_{Z}}{(1+\gamma_{Z})}}$$

where $c_3, c_4 > 0$ are constants independents of n, m_z, δ defined in the proofs.

Bibtex and Bookmarks (Katakis et al., 2008): tag recommendation problems Mediamill: detection of semantic concepts in a video

Data set	n	$n_{\rm te}$	$n_{\rm features}$	n_{labels}
Bibtex	4880	2 515	1836	159
Bookmarks	60 000	27 856	2 150	298
Mediamill	30 993	12 914	120	101

Table 4: Multi-label data sets description.

 Table 5: F1 scores on tag prediction from text data.

Method	Bibtex	Bookmarks	Mediamill
LR	37.2	30.7	NA
SPEN	42.2	34.4	NA
PRLR	44.2	34.9	NA
DVN	44.7	37.1	NA
SISOKR	44.1 ± 0.07	$\textbf{39.3}\pm0.61$	57.26 ± 0.04
ISOKR	44.8 ± 0.01	NA	58.02 ± 0.01
SIOKR	44.7 ± 0.09	39.1 ± 0.04	57.33 ± 0.04
IOKR	44.9	NA	58.17

 Table 6: Training/inference times (in seconds).

Method	Bibtex	Bookmarks	Mediamill
SISOKR	1.41 \pm 0.03 / 0.46 \pm 0.01	118 \pm 1.5 / 20 \pm 0.2	66 ± 0.1 / 4 ± 0.01
ISOKR	2.51 ± 0.06 / 0.58 ± 0.01	NA	$636 \pm 3.7 \ 9 \pm 0.2$
SIOKR	1.99 \pm 0.07 / 1.22 \pm 0.03	354 \pm 2.1 / 297 \pm 2.1	199 \pm 0.1 / 121 \pm 0.02
IOKR	2.54 / 1.18	NA	621 / 204

Inputs: tandem mass spectra of metabolites

Outputs: molecular structures, i.e. fingerprints, encoded by binary vectors of length $d = 7593 \rightarrow$ **probability product kernel**

n = 5579 and each molecule is associated with a specific candidate set: median size = 292 and largest = 36918 fingerprints \rightarrow Gaussian-Tanimoto kernel

Method	kernel loss	Top-1 5 10 accuracies	training	inference
SPEN	0.537 ± 0.008	25.9% 54.1% 64.3%	NA	NA
SISOKR	0.566 ± 0.007	25.1% 54.2% 64.7%	4.05 ± 0.05	1112 ± 29
ISOKR	0.509 ± 0.009	28.0% 58.9% 68.9%	6.25 ± 50.31	1133 ± 32
SIOKR	0.492 ± 0.008	29.5% 61.3% 70.9%	$\textbf{1.25} \pm \textbf{0.02}$	1179 ± 37
IOKR	$\textbf{0.486} \pm \textbf{0.008}$	29.6% 61.6% 71.4%	3.54 ± 0.15	1191 ± 38